# Toward a Cubical Type Theory Univalent by Definition

Hugo Moeneclaey, ENS Paris-Saclay

joint work with:

Hugo Herbelin, INRIA

HoTT 2019



#### Introduction: Cubical Type Theory and Parametricity

Sketching our theory



#### Introduction: Cubical Type Theory and Parametricity

Sketching our theory

# Computing with univalence

Features of Cubical Type Theory [Cohen, Coquand, Huber, Mörtberg 2016]

Apart from an abstract interval, it has:

- Connections allowing to degenerate a path to a square.
- Reversal allowing to go through a path backward.
- Kan compositions generalizing the concatenation of paths.
- Glue types, necessary to prove univalence.

#### Theorem [Huber 2018]

Cubical Type Theory enjoys canonicity.

We present an ongoing attempt to build a variant of Cubical Type Theory where we have *univalence by definition*:

$$(A =_{\mathcal{U}} B) \equiv (A \simeq B)$$

We mainly use ideas from parametricity.

## Parametricity

#### Intuition

Terms built in type theory depend nicely on their type inputs.

Formally: terms send related inputs to related outputs [Reynolds 83].

Applications: Theorems for free! [Wadler 89]

Deduce a result on a polymorphic term from its type.

## An example of parametricity

Assume given  $X_0, X_1 : \mathcal{U}$  and  $X_* : X_0 \to X_1 \to \mathcal{U}$ .

#### Definition

For any simple type A built from X we extend  $X_*$  to:  $A_*: A[X/X_0] \to A[X/X_1] \to \mathcal{U}$ 

by:

$$\begin{array}{rcl} (A \times B)_*((a,a'),(b,b')) &\equiv& A_*(a,a') \times B_*(b,b') \\ (A \to B)_*(f,g) &\equiv& (x_0:A_0) \to (x_1:A_1) \\ & & \to A_*(x_0,x_1) \to B_*(f(x_0),g(x_1)) \end{array}$$

#### Parametricity result

For any simple type A built from X and a such that:

 $\vdash a : A$ 

there exists  $a_*$  such that:

$$\vdash a_* : A_*(a[X/X_0], a[X/X_1])$$

Can be extended to PTS and inductive types [Bernardy, Jansson, Paterson 2010], the crucial point being:

$$\mathcal{U}_*(A,B) \equiv A \to B \to \mathcal{U}$$

## Internal parametricity

Parametricity is external, but it can be internalized.

#### Parametric Type Theory [Bernardy, Coquand, Moulin 2015]

Strikingly similar to Cubical Type Theory. We denote by  $x \sim_A y$  the analogue to path types. We have the relativity axiom, in this case:

$$(A \sim_{\mathcal{U}} B) \cong (A \rightarrow B \rightarrow \mathcal{U})$$

where  $\_\cong\_$  stands for definitional isomorphism.

They use predicates rather than relations.

## Parametricity and higher dimensional type theory

Ideas flow both ways:

#### Examples

 [Cavalo, Harper 2018] presents a type theory both Parametric and Higher-dimensional. Relativity is formulated as:

$$(A \sim_{\mathcal{U}} B) \simeq (A \rightarrow B \rightarrow \mathcal{U})$$

- [Altenkirch, Kaposi 2017] presents ideas toward a higher dimensional type theory without interval, inspired by parametricity.
- [Tabareau, Tanter, Sozeau 2017] implements ideas from parametricity in order to mechanize the transfer of some libraries along equivalences in Coq.

#### Examples with extensionality

- In Observational Type Theory [Altenkirch, McBride, Swierstra 2007] identity types are defined by induction on a a closed universe.
- XTT [Angiuli, Gratzer, Sterling 2019] uses cubical techniques, but two paths with the same endpoints are definitionally equal.



#### Introduction: Cubical Type Theory and Parametricity

Sketching our theory

We start with all the rules for a type theory with:

- $\Sigma$  and  $\Pi$  with  $\eta$ -rules.
- ► A hierarchy of universes, all denoted U.

## Heterogeneous path types

We denote  $\_=_{\lambda i.A}$  by  $\_=_{A}$  when *i* does not occur in *A*.

#### Definition

We add heterogeneous path types:

$$\frac{\Gamma \vdash \epsilon : X =_{\mathcal{U}} Y}{\Gamma \vdash \_ =_{\epsilon} \_ : X \to Y \to \mathcal{U}}$$

$$\frac{1, i \vdash t : A}{\Gamma \vdash \lambda i.t : t[i/0] =_{\lambda i.A} t[i/1]}$$

$$\frac{\Gamma, i, \Gamma' \vdash p : s =_{\epsilon} t}{\Gamma, i, \Gamma' \vdash p(i) : \epsilon(i)}$$

For  $p: a_0 =_{\epsilon} a_1$ , we define (p(i))[i/u] as  $a_u[i/u]$  where  $u \in \{0, 1\}$ .

## Equivalences

#### Definition

An equivalence  $\epsilon : A \simeq B$  consists of a relation  $R : A \rightarrow B \rightarrow U$ with contractible fibers. In particular we have:

- ▶ Functions  $\overrightarrow{\epsilon} : A \to B$  and  $\overrightarrow{\epsilon} : (x : A) \to R(x, \overrightarrow{\epsilon}(x))$ .
- ▶ Functions  $\overleftarrow{\epsilon} : B \to A$  and  $\overleftarrow{\epsilon} : (y : B) \to R(\overleftarrow{\epsilon}(y), y)$ .

We add:

$$(X =_{\mathcal{U}} Y) \equiv (X \simeq Y)$$

We identify  $\_ =_{\epsilon} \_$  with the underlying relation of  $\epsilon : A =_{\mathcal{U}} B$ .

Computing with path types: some examples

For product types we add:

$$\begin{array}{rcl} (a,b) =_{\lambda i.A \times B} (a',b') &\equiv & (a =_{\lambda i.A} a') \times (b =_{\lambda i.B} b') \\ \hline \lambda i.A \times B(a,b) &\equiv & \left(\overline{\lambda i.A}(a), \overline{\lambda i.B}(b)\right) \\ \hline \overrightarrow{\lambda i.A \times B}(a,b) &\equiv & \left(\overrightarrow{\lambda i.A}(a), \overrightarrow{\lambda i.B}(b)\right) \\ & (\lambda i.c).1 &\equiv & \lambda i.(c.1) \\ & (p,q)(i) &\equiv & (p(i),q(i)) \end{array}$$

For function types we add:

$$f =_{\lambda i.A \to B} g \equiv (x_0 : A[i/0]) \to (x_1 : A[i/1])$$
  

$$\rightarrow x_0 =_{\lambda i.A} x_1 \to f(x_0) =_{\lambda i.B} g(x_1)$$
  

$$\overrightarrow{\lambda i.A \to B}(f) \equiv \overrightarrow{\lambda i.B} \circ f \circ \overleftarrow{\lambda i.A}$$
  

$$(\lambda i.f)(a_0, a_1, a_*) \equiv \lambda i.f(a_*(i))$$
  

$$(\lambda a_0, a_1, a_*.t)(i) \equiv ?$$

Computing with path types: regularity

When i does not occur in A, we add:

$$\overrightarrow{\lambda i.A} \equiv \lambda(x:A). x$$

$$\overrightarrow{\overrightarrow{\lambda i.A}} \equiv \lambda(x:A). \operatorname{refl}_{x}$$

#### Warning

This is not known to be consistent with univalence.

## Toward full computation

#### How to add type formers

For any type former T, we need to give computation rules for:

• Components of the equivalence  $\lambda i. T(A, B)$ , for example:

$$t_1 =_{\lambda i.T(A,B)} t_2 \equiv C(t_1, t_2, \lambda i.A, \lambda i.B)$$

- $\operatorname{elim}_{=}(\lambda i.t)$  with  $\operatorname{elim}_{=}$  eliminator of C.
- $cons_{=}(t)(i)$  with  $cons_{=}$  constructor of C.

We have all rules for  $\Sigma$  and  $\Pi$ , except for:

$$(\lambda a_0, a_1, a_*. t)(i)$$

These rules respect regularity.

## A guess for normal forms

We write  $\operatorname{Equiv}(\epsilon)$  for the second projection of  $\epsilon : A =_{\mathcal{U}} B$ . We write  $\langle \_, \cdots, \_ \rangle$  for the constructor of equivalences.

Definition

We define the set neutral terms N and values V by induction:

$$N := x | N(i) | N.1 | N.2 | N(V) |$$
  
=  $\sum_{\lambda i.N} - | \text{Equiv}(\lambda i.N) | \langle V, \cdots, V \rangle(i)$ 

$$V := N \mid \lambda i.V \mid (V,V) \mid \lambda x.V \mid$$
$$\Sigma(x:V).V \mid \Pi(x:V).V \mid U$$

## Toward interpretation

How to justify this theory?

Iterated parametricity

We hope for a translation similar to parametricity, but with:

$$\mathcal{U}_*(A,B) \equiv A \simeq B$$

Then this translation should be iterated once per dimension name.

## Further work

- We need to solve the problem with Π-types.
- ▶ We need to give an interpretation. Is regularity consistent?
- What about confluence, normalization, canonicity?
- What about inductive types? And higher inductive types?
- Can we internalize parametricity similarly?
- Can we internalize other principles this way?